# Effects of Strengths of Steel and Concrete, Eccentricity and Bar Size on the Optimization of Eccentrically Loaded Footings 

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#### Abstract

This paper aims to explore effects of the yield strength of steel, compressive strength of concrete, eccentricity of the axial load and steel bar size on the optimization of reinforced concrete isolated footings. The optimization tool adopted in this paper is genetic algorithms. Based on the ACI Building Code, constraints are built by considering the wide-beam and punching shears, bending moment, upper and lower limits of reinforcement, allowable soil pressure, development length for deformed bars and clear distance between parallel deformed bars. Design variables consist of the width, length and thickness of the footing and the number of bars in the long and short directions, all of which are integers. The objective is to minimize the cost of steel and concrete used in the footing. By changing one of the four factors: the yield strength of steel, compressive strength of concrete, eccentricity and bar size while fixing the other three, this paper finds that the highest yield strength of steel, the lowest compressive strength of concrete, the smallest eccentricity and No. 6 bar, respectively, will lead to the optimal results. In addition, when the size of the reinforcement gets larger, the optimal footing have a tendency to become square and thicker.


Keywords: Genetic Algorithms; Optimal Design; Reinforced Concrete Footings; Eccentricity

## 1 Introduction

A footing that serves the purpose of transmitting the load from the superstructure to the supporting soil is a very important element in an architectural structure. A conventional way to design a footing is to find its suitable dimensions and amount of reinforcement according to the provisions of a building code. The design results are usually not the most economical. In order to achieve this goal, the optimization techniques can be applied. There have been a number of optimization studies of reinforced concrete footings published over the past few years, such as optimization of combined footings using modified complex method of box [1], optimization of concentrically loaded reinforced concrete footing using an analytical model [2], and optimization of concentrically loaded reinforced concrete footings using genetic algorithms [3].

The fundamental techniques of genetic algorithms are designed to imitate processes in natural evolution. Genetic algorithms are the most effective methods in a search space for which little is known and which is uneven and has many hills and valleys with potential candidate solutions. The idea of genetic algorithms was inspired by the evolution theory of "survival of the fittest," and formally introduced in 1970s by Professor John Holland at the University of Michigan, who in 1975 published the ground-breaking book "Adaptation in Natural and Artificial System" [4] that led to many important discoveries. In 1989, Goldberg
DOI: 10.14738/tmlai.55.3592
Publication Date: $27^{\text {th }}$ August, 2017
URL: http://dx.doi.org/10.14738/tmlai.55.3592
described in more detail the theory of genetic algorithms and its applications [5]. From then on, the continuing improvements of computational techniques have made genetic algorithms more attractive and popular. Genetic algorithms have successfully been applied to many fields, for example, engineering, economics, chemistry, manufacturing, mathematics and physics. Especially in the aspect of engineering structures, there are a lot of applications, such as reliability analysis of structures [6], global optimization of grillages [7], global optimization of trusses with a modified genetic algorithm [8], optimization of pile groups using hybrid genetic algorithms [9], prediction of concrete faced rock fill dams settlements [10], optimization of grid shell topology and nodal positions [11], optimizations of constrained layered damped (CLD) laminated structures [12], calibration of a hydrological model to predict stream flows [13] and optimal design of short columns [14].The fact that they are successfully applied to many problems which are difficult to solve by using conventional optimization techniques prove that genetic algorithms are a powerful, robust optimization technique.

Most optimization approaches have been focused on and developed for continuous variables, while the design variables are usually integers for problems in architectural structures. Due to their abilities to solve discrete optimization problems, genetic algorithms provided by the MATLAB Global Optimization Toolbox [15] are used in this paper to carry out the optimization of eccentrically loaded reinforced concrete isolated footings and explore effects of the yield strength of steel, compressive strength of concrete, bar size and eccentricity on the optimal results. Based on the provisions of the ACI Building Code Requirements for Structural Concrete and Commentary [16], the constraints of genetic algorithms are constructed, considering the wide-beam and punching shears, bending moment, upper and lower limits of reinforcement, allowable soil pressure, development length for deformed bars, clear distance between deformed bars. The design variables are the depth, width and length of the footing, the number of bending reinforcement in each direction of the footing; the objective is to find the minimum cost of concrete and steel.

## 2 Genetic Algorithms

Genetic algorithms are basically a heuristic process for mimicking the survival of the fittest among individuals over a sequence of generations for solving an optimization problem. There is a population of individuals in each generation. Each individual made up of design variables represents a candidate solution to a given problem. The individuals are similar to chromosomes and the design variables to genes. A fitness value is assigned to each solution to measure its competitiveness. The individuals with higher fitness values are more likely to be selected to form the next generation. If the current population can no more produce individuals significantly better than those in the previous few generations, the algorithm is said to converge and the optimal solution are found.

The most common type of genetic algorithms works through the following process of natural selection: (1) Randomly create an initial population of individuals; (2) Score each individual of the current population by computing the value of the fitness function; (3) Scale the raw fitness scores to convert them into a range that is suitable for the selection function; (4) Select a specified number of individuals with lower fitness values, called parents, by using the selection function; (5) Choose a few elite individuals with the lowest fitness values from the current population. These elite individuals are then just passed to the next population; (6) Produce children from the parents. Children are produced either by combining portions of good individuals (i.e., crossover), which aims to create even better individuals or making random changes to a single individual (i.e., mutation), whose purpose is to maintain diversity within the population and
inhibit premature convergence; (7) Replace the current population with the crossover and mutation children and elites to form the next generation and the process repeats form steps (2) to (7). The algorithm stops when one of the stopping criteria is met, such as the number of generation, the weighted average change in the fitness function value over some generations less than a specified tolerance, no improvement in the best fitness value for an interval of time, etc. Genetic algorithms can solve both constrained and unconstrained optimization problems. The constraints built for genetic algorithms can be linear or nonlinear in the form of equality or inequality with bounds on the variables. Each individual made up of the design variables can be real-coded or binary-coded. In this paper, the constraints consist of nonlinear and linear inequalities and all the design variables are integers.

## 3 Design Considerations in Eccentrically Loaded Footings

Both the concentric compressive force $P_{u}$ and bending moment $M_{u}$, are considered to act on the reinforced concrete isolated footing whose layout is shown in Fig. 1. The rectangular footing has width $B$, length $L$ and thickness $h$, and the column size is $a \times b$. The soil bearing pressure distribution on the footing is trapezoidal due to the combined effects of axial load and bending, as shown in Fig. 1(a). All the constraints required to design the isolated footing comply with the ultimate-strength design of ACI 31811 Code, considering wide-beam and punching shears, bending moment, the development length for deformed bars, clear distance between parallel deformed bars and the upper and lower limits of reinforcement. The units of force and length in the following formulas are kgf ( $=9.81 \mathrm{~N}$ ) and cm , respectively. The factored load $P_{u}=1.2 P_{D}+1.6 P_{L}$,


Figure 1 The reinforced concrete footing subjected to the concentric factored load Pu and bending moment Mu: (a) elevation and (b) plan

Figure 1 The reinforced concrete footing subjected to the concentric factored load $P_{u}$ and bending moment $M_{u}$ : (a) elevation and (b) plan.
where $P_{D}$ and $P_{L}$ are the dead and live loads, respectively. The eccentricity $e$ is defined as $M_{u} / P_{u}$.

### 3.1 Factored Shears

To have enough shear capacity, there are two kinds of actions that need to be considered: wide-beam action and two-way action.

### 3.1.1 Wide-beam Action

The maximum and minimum soil pressures on the footing, as shown in Fig. 1, are

$$
\begin{equation*}
q_{u \max }=\frac{P_{u}}{L B}\left(1+\frac{6 e}{L}\right) \tag{1}
\end{equation*}
$$

and

$$
\begin{equation*}
q_{u \min }=\frac{P_{u}}{L B}\left(1-\frac{6 e}{L}\right) \tag{2}
\end{equation*}
$$

respectively, where $e \leq \frac{L}{6}$ is the eccentricity. The plane of the critical section is assumed to extend in a plane across the entire width and lies at a distance $d$ from the face of the column, as shown in Fig. 2(a). The nominal shear strength of this section is

$$
\begin{equation*}
V_{c 1}=0.53 \sqrt{f_{c}^{\prime}} B d \tag{3}
\end{equation*}
$$

and

$$
\begin{equation*}
V_{c 2}=0.53 \sqrt{f_{c}^{\prime \prime}} L d \tag{4}
\end{equation*}
$$

respectively in the long and short directions, where $d$ is the average effective depth of the footing. Let $q_{u d L}$ denote the soil pressure in the long direction of the footing at a distance $d$ from the right face of the column and $\phi=0.75$ be the strength reduction factor for shear. The constraints for the wide-beam shear are

$$
\begin{equation*}
V_{u L}=q_{u a v g L}\left(\frac{L-a}{2}-d\right) B \leq \phi V_{c 1} \tag{5}
\end{equation*}
$$

and

$$
\begin{equation*}
V_{u B}=q_{u_{a v g B}}\left(\frac{B-b}{2}-d\right) L \leq \phi V_{c 2} \tag{6}
\end{equation*}
$$

respectively for the long and short directions of the footing, where

$$
\begin{equation*}
q_{u a v g L}=\frac{q_{u \max }+q_{u d L}}{2} \tag{7}
\end{equation*}
$$

and

$$
\begin{equation*}
q_{u a v g B}=\frac{q_{u \max }+q_{u \min }}{2} \tag{8}
\end{equation*}
$$

### 3.1.2 Two-way Action

The critical section occurs at a distance $d / 2$ from the face of the column, as shown in Fig. 2 (b). The maximum allowable nominal shear strength is the smallest of the following three equations

$$
\begin{align*}
& V_{c}=\left(0.53+\frac{1.06}{\beta_{c}}\right) \sqrt{f_{c}^{\prime}} b_{0} d, \\
& V_{c}=\left(0.53+\frac{0.265 \alpha_{s} d}{b_{0}}\right) \sqrt{f_{c}^{\prime}} b_{0} d  \tag{9}\\
& V_{c}=1.06 \sqrt{f_{c}^{\prime}} b_{0} d
\end{align*}
$$

where $\beta_{c}=$ long side $a /$ short side $b$ of the concentrated load or reaction area, $b_{0}=$ perimeter of the critical section CDEF and $\alpha_{s}=40,30$ and 20 for interior, edge and corner columns, respectively. In this paper, interior columns are considered; therefore, $\alpha_{s}=40$. Let $q_{u L 1}$ and $q_{u L 2}$ denote the soil pressures at a distance $d / 2$ from the left and right faces of the column, respectively. The constraint for the punching shear is

$$
\begin{equation*}
V_{u}=P_{u}-\frac{q_{u L 1}+q_{u L 2}}{2}(a+d)(b+d) \leq \phi V_{c, \min } \tag{10}
\end{equation*}
$$

where $V_{c, \text { min }}$ is the smallest of Eqs. (9).


Figure $\mathbf{2}$ Critical sections: (a) wide-beam action and (b) two-way action.

### 3.2 Factored Moments

Suppose that $N_{L}$ and $N_{B}$ are the number of steel bars required in the long and short directions of the footing, respectively, and $A_{b}$ is the cross-sectional area of the flexural reinforcement. The critical section for moment is taken at the face of the column. Let $q_{u l 3}$ denote the soil pressure at the right face of the column. The constraints for the factored moments are

$$
\begin{equation*}
M_{u L}=\frac{\left(q_{u L 3}+q_{u \max }\right) B}{2}\left(\frac{L-a}{2}\right) k \leq \phi_{m L} N_{L} A_{b} f_{y}\left(d-\frac{N_{L} A_{b} f_{y}}{2(0.85) f_{c}^{\prime B}}\right) \tag{11}
\end{equation*}
$$

and

$$
\begin{equation*}
M_{u B}=\frac{\left(q_{u \max }+q_{u \min }\right) L}{2} \frac{(B-b)^{2}}{8} \leq \phi_{m B} N_{B} A_{b} f_{y}\left(d-\frac{N_{B} A_{b} f_{y}}{2(0.85) f_{c}^{\prime} L}\right) \tag{12}
\end{equation*}
$$

where $\phi_{m L}$ and $\phi_{m B}$ are the strength reduction factors for moment and $k$ is distance from the face of the column to the centroid of the trapezoid. Let $\varepsilon_{t}$ be the tensile strain of the reinforcement, then

$$
\begin{equation*}
0.65 \leq \phi_{m L} \text { or } \phi_{m B}=0.65+0.25 \frac{\varepsilon_{t}-\varepsilon_{y}}{0.005-\varepsilon_{y}} \leq 0.9 \tag{13}
\end{equation*}
$$

### 3.3 Upper and Lower Limits of Reinforcement

To prevent sudden failure with little or no warning when the beam cracks or fails in a brittle manner, the ACI code limits the minimum and maximum amount of steel to be

$$
\begin{equation*}
A_{s L, \min } \leq N_{L} A_{b} \leq A_{s L, \max }=\frac{0.85 f_{c}^{\prime} \beta B d}{f_{y}}\left(\frac{3}{7}\right) \tag{14}
\end{equation*}
$$

and

$$
\begin{equation*}
A_{s B, \min } \leq N_{B} A_{b} \leq A_{s B, \max }=\frac{0.85 f_{c}^{\prime} \beta L d}{f_{y}}\left(\frac{3}{7}\right) \tag{15}
\end{equation*}
$$

respectively in the long and short directions, where $\beta$ is the stress block depth factor,

$$
\begin{equation*}
A_{s L, \min } \geq \max \left(\frac{0.8 \sqrt{f_{c}^{\prime}}}{f_{y}} B d, \frac{14 B d}{f_{y}}\right) \tag{16}
\end{equation*}
$$

and

$$
\begin{equation*}
A_{s B, \min } \geq \max \left(\frac{0.8 \sqrt{f_{c}^{\prime}}}{f_{y}} L d, \frac{14 L d}{f_{y}}\right) \tag{17}
\end{equation*}
$$

The formula for $A_{s L, \max }$ in Eq. (14) and $A_{s B, \text { max }}$ in Eq. (15) is derived based on the requirement that the tensile strain must be greater than or equal to 0.004 . In addition, both the steel ratios $N_{L} A_{b} /(B h)$ and $N_{B} A_{b} /(L h)$ must exceed the minimum value required for temperature and shrinkage: 0.0018 for grade 60 deformed bars and 0.002 for grade 40 or 50 deformed bars.

### 3.4 Allowable Bearing Capacity of Soil

Bearing capacity is the capacity of soil to support the loads applied to the ground. Usually, only the service loads need to be considered, i.e., $P_{D}$ and $P_{L}$ without load factors. Assume that the allowable soil pressure under the base of the footing is $q_{a}$. The gross soil pressure must not exceed the allowable soil pressure, that is,

$$
\begin{equation*}
\frac{P_{D}+P_{L}}{B L}+h w_{c}+\gamma_{s}\left(D_{f}-h\right) \leq q_{a} \tag{18}
\end{equation*}
$$

where $D_{f}$ is the distance from the base of the footing to the ground surface, as shown in Fig. $1, w_{c}$ is the weight of concrete and $\gamma_{s}$ is the unit weight of soil over the footing.

### 3.5 Development Length for Deformed Bars

The ACl Code specifies that the equation for the development of deformed bars in tension be expressed by

$$
\begin{align*}
L_{d} & =\frac{0.15 d_{b} f_{y} \psi_{t} \psi_{e} \lambda}{\sqrt{f_{c}^{\prime}}} \geq 30 \mathrm{~cm}  \tag{19}\\
\text { or } \quad L_{d} & =\frac{0.19 d_{b} f_{y} \psi_{t} \psi_{e} \lambda}{\sqrt{f_{c}^{\prime}}} \geq 30 \mathrm{~cm} \tag{20}
\end{align*}
$$

for No. 6 and smaller bars or No. 7 and larger bars, respectively, with clear spacing not less than $2 d_{b}$ and clear cover not less than $d_{b}$, where $d_{b}$ is the bar diameter, and $\psi_{t}$ and $\psi_{e}$ are the bar location and coating factors, respectively. In this paper $\psi_{\mathrm{t}}$ and $\psi_{\mathrm{e}}$ are assumed to be 1.0 and $\lambda=1$ for normal weight concrete. The critical section for development length of the bars in tension is the same as the critical section in flexure, that is, at the face of the column. Hence,

$$
\begin{equation*}
0.5(L-a) \text { - concrete cover } \geq L_{d} \tag{21}
\end{equation*}
$$

and

$$
\begin{equation*}
0.5(B-b)-\text { concrete cover } \geq L_{d} \tag{22}
\end{equation*}
$$

respectively in the long and short directions. The equation for the development length of bars in compression is

$$
\begin{equation*}
L_{d c}=\max \left(\frac{0.075 d_{b} f_{y}}{\sqrt{f_{c}^{\prime}}}, 0.0043 d_{b} f_{y}\right) \tag{23}
\end{equation*}
$$

The dowel bars stressed to $f_{y}$ are required to transfer the axial compression force in the column into the footing, as shown in Fig. 1; hence, there should be minimum extension of the dowels into the footing. Therefore, the thickness $h$ of the footing must satisfy the following constraints:

$$
\begin{equation*}
h \text { - concrete cover }-2 d_{b} \text { (footing bars) }-d_{b} \text { (dowels) } \geq L_{d c} \tag{24}
\end{equation*}
$$

In addition, depth of footing above bottom reinforcement shall not be less than 15 cm for footings on soil and a practical minimum thickness $h$ should not be less than 25 cm .

### 3.6 Distribution and Minimum Clear Distance of Steel Bars

The total steel area $N_{B} A_{b}$ in the short direction determined from Eqs. (12) and (15) should be uniformly distributed over the central band of the footing, whose width is $B$, as shown in Fig. 3. The ratio of the reinforcement in the central band to the total reinforcement is equal to $2 /(L / B+1)$. The reinforcement that is not placed in the central band is uniformly spaced at each side of the central band. In the long direction, the total steel area $N_{L} A_{b}$ determined from Eqs. (11) and (14) is uniformly distributed across the entire width of the footing. The clear distance $s$ between parallel steel bars in both the long and short directions must satisfy

$$
\begin{equation*}
\operatorname{Min}(3 h, 45 \mathrm{~cm}) \geq s \geq \operatorname{Max}\left(2 d_{b}, 2.5 \mathrm{~cm}\right) \tag{25}
\end{equation*}
$$

Instead of $d_{b}$, the minimum clear distance $2 d_{b}$ used in Eq. (25) is due to the requirement of Eqs. 19 and 20.


Figure 3 The central band of the footing.

## 4 Numerical Results

The given design conditions for the eccentrically loaded footings are as follows: the dead load $P_{D}=100$ ton, the live load $P_{L}=80$ ton, the distance from the footing bottom to the ground surface $D_{f}=1.5 \mathrm{~m}$, the unit weight of concrete $\gamma_{\mathrm{c}}=2.4 \mathrm{ton} / \mathrm{m}^{3}$, the unit weight of soil over the footing $\gamma_{\mathrm{s}}=2 \mathrm{ton} / \mathrm{m}^{3}$ and the allowable soil pressure at the base of the footing $q_{a}=25$ ton $/ \mathrm{m}^{2}$. The size of the column transferring the axial load and eccentric moment to the footing is assumed to be $0.40 \mathrm{~m} \times 0.40 \mathrm{~m}$. The concrete cover for the reinforcement of the footing is assumed to be 7.5 cm . In order to explore their effects on the optimization of eccentrically loaded footings, the yield strength of steel $f_{y}$, compressive strength of concrete $f_{c}^{\prime}$, size of the flexural reinforcement or eccentricity $e$ is varied, with the other three fixed. In Taiwan, the unit price of concrete is $1950 \mathrm{NT} \$ / \mathrm{m}, 2150 \mathrm{NT} \$ / \mathrm{m}^{3}, 2350 \mathrm{NT} \$ / \mathrm{m}^{3}$ and $2450 \mathrm{NT} \$ / \mathrm{m}^{3}$ for $f_{c}^{\prime}=210 \mathrm{kgf} / \mathrm{cm}^{2}(3000 \mathrm{psi})$, $280 \mathrm{kgf} / \mathrm{cm}^{2}$ ( 4000 psi ), $350 \mathrm{kgf} / \mathrm{cm}^{2}$ ( 5000 psi ) and $420 \mathrm{kgf} / \mathrm{cm}^{2}$ ( 6000 psi ), respectively; the unit price of steel is $14400 \mathrm{NT} \$ /$ ton. Design variables are the thickness $h$, width $B$ and length $\angle$ of the footing, and the number of steel bars in the long direction $N_{L}$ and short direction $N_{B}$. In this paper, there are six kinds of bar sizes: Nos. 4 to 9 ; four kinds of $f_{c}^{\prime}: 210 \mathrm{kgf} / \mathrm{cm}^{2}, 280 \mathrm{kgf} / \mathrm{cm}^{2}, 350 \mathrm{kgf} / \mathrm{cm}^{2}$ and $420 \mathrm{kgf} / \mathrm{cm}^{2}$; three kinds of $f_{y}: 2800 \mathrm{kgf} / \mathrm{cm}^{2}(40 \mathrm{ksi}), 3500 \mathrm{kgf} / \mathrm{cm}^{2}(50 \mathrm{ksi})$ and $4200 \mathrm{kgf} / \mathrm{cm}^{2}(60 \mathrm{ksi})$; and seven kinds of eccentricity: $0 \mathrm{~cm}, 10 \mathrm{~cm}, 20 \mathrm{~cm}, 30 \mathrm{~cm}, 40 \mathrm{~cm}, 50 \mathrm{~cm}$ and 60 cm . The fitness function is the total cost in New Taiwan Dollars of the footing reinforcement and concrete. All the constraints are built according to the formulas discussed in Sec. 3. The population size is set to be 100, crossover rate 0.8, and elite number 5. Furthermore, all the individuals are encoded as integers; "Rank" is used as the scaling function that scales the fitness values based on the rank of each individual; "Roulette" is the selection function to choose parents for the next generation; "Two-point crossover" is used as the crossover method to form a new child for the next generation; The "Adaptive Feasible Function" is selected as the mutation function. The results are discussed as follows.

### 4.1 Optimal Results by Fixing $f_{y}=4200 \mathrm{kgf} / \mathrm{cm}^{2}, \boldsymbol{f}_{\boldsymbol{c}}{ }^{\prime}=\mathbf{2 1 0} \mathbf{~ k g f} / \mathrm{cm}^{2}$ and $\boldsymbol{e}=\mathbf{1 0} \mathbf{~ c m}$

The size of reinforcement is varied, ranging from No. 4 to No. 9. The optimal results are listed in Table 1, where No. 6 reinforcement has the minimum cost. The lowest cost can be seen clearly in Fig. 4. In addition, when the size of the reinforcement becomes larger, the optimal footing grows square and thicker, as shown in Fig. 5.

### 4.2 Optimal Results by Fixing $\boldsymbol{f}_{\boldsymbol{c}} \boldsymbol{c}^{\prime}=\mathbf{2 1 0} \mathbf{~ k g f} / \mathrm{cm}^{2}$, No. 6 bar and $\boldsymbol{e}=\mathbf{1 0} \mathbf{~ c m}$

There are three kinds of yield strengths of steel: $f_{y}=4200 \mathrm{kgf} / \mathrm{cm}^{2}, 3500 \mathrm{kgf} / \mathrm{cm}^{2}$ and $2800 \mathrm{kgf} / \mathrm{cm}^{2}$. The optimal results are listed in Table 2, where $f_{y}=4200 \mathrm{kgf} / \mathrm{cm}^{2}$ has the minimum cost. Besides, when $f_{y}$ changes, the optimal thickness remains the same.

### 4.3 Optimal Results by Fixing $f_{y}=4200 \mathrm{kgf} / \mathrm{cm}^{2}$, No. 6 bar and $\boldsymbol{e}=10 \mathrm{~cm}$

There are four kinds of compressive strengths of concrete: $f_{c}^{\prime}=210 \mathrm{kgf} / \mathrm{cm}^{2}, 280 \mathrm{kgf} / \mathrm{cm}^{2}, 350 \mathrm{kgf} / \mathrm{cm}^{2}$ and $420 \mathrm{kgf} / \mathrm{cm}^{2}$. The results are listed in Table 3, where $f_{c}^{\prime}=210 \mathrm{kgf} / \mathrm{cm}^{2}$ has the minimum cost. Besides, when $f_{c}^{\prime}$ becomes larger, the thickness of the footing turns to be smaller.

### 4.4 Optimal Results by Fixing $f_{y}=\mathbf{4 2 0 0} \mathbf{~ k g f} / \mathrm{cm}^{2}, \boldsymbol{f}_{\boldsymbol{c}}{ }^{\boldsymbol{\prime}}=\mathbf{2 1 0} \mathbf{~ k g f} / \mathrm{cm}^{2}$ and No. $\mathbf{6} \mathbf{~ b a r}$

There are seven kinds of eccentricity explored: $e=0 \mathrm{~cm}, 10 \mathrm{~cm}, 20 \mathrm{~cm}, 30 \mathrm{~cm}, 40 \mathrm{~cm}, 50 \mathrm{~cm}$ and 60 cm . The results are listed in Table 4, which shows the smaller the eccentricity is, the less cost the footing becomes. Aside from that, when the eccentricity becomes bigger, the optimal footing turns to be thicker.

Table 1 Optimal results by fixing $f_{y}=4200 \mathrm{kgf} / \mathrm{cm}^{2}$,
$f_{c}{ }^{\prime}=210 \mathrm{kgf} / \mathrm{cm}^{2}$ and $e=10 \mathrm{~cm}$.

| Bar size | $h$ <br> $(\mathrm{~cm})$ | $B$ <br> $(\mathrm{~cm})$ | $L$ <br> $(\mathrm{~cm})$ | $N_{B}$ | $N_{L}$ | Cost <br> $(\mathrm{NT}$ ) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No. 4 | 62 | 270 | 307 | 43 | 38 | 13,188 |
| No. 5 | 62 | 266 | 311 | 28 | 24 | 13,180 |
| No. 6 | 62 | 261 | 317 | 20 | 16 | 13,166 |
| No. 7 | 63 | 300 | 300 | 14 | 14 | 14,547 |
| No. 8 | 71 | 335 | 335 | 14 | 14 | 20,672 |
| No. 9 | 79 | 372 | 372 | 14 | 14 | 28,628 |



Figure 4 The optimal prices for different bar sizes


Figure 5 The Optimal Results of thickness, width and length for different bar sizes

Table 2 Optimal results by fixing $f_{c}^{\prime}=210 \mathrm{kgf} / \mathrm{cm}^{2}$, No. 6 bar and $e=10 \mathrm{~cm}$.

| $f_{y}$ <br> $\left(\mathrm{kgf} / \mathrm{cm}^{2}\right)$ | $h$ <br> $(\mathrm{~cm})$ | $B$ <br> $(\mathrm{~cm})$ | $L$ <br> $(\mathrm{~cm})$ | $N_{B}$ | $N_{L}$ | Cost <br> $(\mathrm{NT} \$)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2800 | 62 | 282 | 294 | 27 | 26 | 14,715 |
| 3500 | 62 | 257 | 322 | 24 | 19 | 13,781 |
| 4200 | 62 | 261 | 317 | 20 | 16 | 13,166 |

Table 3 Optimal results by fixing $f_{y}=4200 \mathrm{kgf} / \mathrm{cm}^{2}$, No. 6 bar and $e=10 \mathrm{~cm}$.

| $f_{c}^{\prime}$ <br> $\left(\mathrm{kgf} / \mathrm{cm}^{2}\right)$ | $h$ <br> $(\mathrm{~cm})$ | $B$ <br> $(\mathrm{~cm})$ | $L$ <br> $(\mathrm{~cm})$ | $N_{B}$ | $N_{L}$ | Cost <br> $(\mathrm{NT} \$)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 210 | 62 | 261 | 317 | 20 | 16 | 13,166 |
| 280 | 58 | 275 | 301 | 17 | 16 | 13,240 |
| 350 | 55 | 281 | 294 | 17 | 17 | 13,683 |
| 420 | 52 | 285 | 290 | 17 | 17 | 13,535 |

Table 4 Optimal results by fixing fy $=4200 \mathrm{kgf} / \mathrm{cm} 2, \mathrm{fc}^{\prime}=210 \mathrm{kgf} / \mathrm{cm} 2$ and No. 6 bar.

| $e$ <br> $(\mathrm{~cm})$ | $h$ <br> $(\mathrm{~cm})$ | $B$ <br> $(\mathrm{~cm})$ | $L$ <br> $(\mathrm{~cm})$ | $N_{B}$ | $N_{L}$ | Cost <br> $(\mathrm{NT} \$)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 62 | 261 | 317 | 20 | 16 | 13,166 |
| 10 | 62 | 261 | 317 | 20 | 16 | 13,166 |
| 20 | 62 | 275 | 301 | 19 | 17 | 13,187 |
| 30 | 64 | 284 | 292 | 19 | 19 | 13,715 |
| 40 | 67 | 286 | 290 | 20 | 20 | 14,378 |
| 50 | 72 | 277 | 300 | 22 | 21 | 15,478 |
| 60 | 86 | 231 | 361 | 33 | 21 | 18,724 |

## 5 Conclusions

This paper explores effects of the yield strength of steel, compressive strength of concrete, bar size and eccentricity of the axial load transmitted to the footing on the optimization of reinforced concrete isolated footings. Genetic algorithms are used to optimally design the eccentrically loaded reinforced concrete footings. From the numerical results, the principal conclusions may be summarized as follows:
(1) The steel yield strength of $4200 \mathrm{kgf} / \mathrm{cm}^{2}$, the concrete compressive strength of $210 \mathrm{kgf} / \mathrm{cm}^{2}$, the smallest eccentricity and No. 6 bar, respectively, will have the optimal results if one of them is varied and the other three are fixed.
(2) When the size of the reinforcement is getting larger, the optimal footing have a tendency to become square and thicker.
(3) When $f_{y}$ changes, the optimal thickness of the footing remains the same.
(4) When $f_{c}^{\prime}$ becomes larger, the optimal footing is getting thinner.
(5) When the eccentricity becomes bigger, the optimal footing grows thicker.

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